



# PCA9544A

## 4-channel I<sup>2</sup>C-bus multiplexer with interrupt logic

Rev. 5 — 23 April 2014

Product data sheet

## 1. General description

The PCA9544A is a 1-of-4 bidirectional translating multiplexer, controlled via the I<sup>2</sup>C-bus. The SCL/SDA upstream pair fans out to four SCx/SDx downstream pairs, or channels. Only one SCx/SDx channel is selected at a time, determined by the contents of the programmable control register. Four interrupt inputs,  $\overline{INT0}$  to  $\overline{INT3}$ , one for each of the SCx/SDx downstream pairs, are provided. One interrupt output,  $\overline{INT}$ , which acts as an AND of the four interrupt inputs, is provided.

A power-on reset function puts the registers in their default state and initializes the I<sup>2</sup>C-bus state machine with no channels selected.

The pass gates of the multiplexer are constructed such that the  $V_{DD}$  pin can be used to limit the maximum high voltage which is passed by the PCA9544A. This allows the use of different bus voltages on each SCx/SDx pair, so that 1.8 V, 2.5 V or 3.3 V parts can communicate with 5 V parts without any additional protection. External pull-up resistors pull the bus up to the desired voltage level for each channel. All I/O pins are 5 V tolerant.

## 2. Features and benefits

- 1-of-4 bidirectional translating multiplexer
- I<sup>2</sup>C-bus interface logic; compatible with SMBus
- 4 active LOW interrupt inputs
- Active LOW interrupt output
- 3 address pins allowing up to 8 devices on the I<sup>2</sup>C-bus
- Channel selection via I<sup>2</sup>C-bus
- Power-up with all multiplexer channels deselected
- Low  $R_{on}$  switches
- Allows voltage level translation between 1.8 V, 2.5 V, 3.3 V and 5 V buses
- No glitch on power-up
- Supports hot insertion
- Low standby current
- Operating power supply voltage range of 2.3 V to 5.5 V
- 5 V tolerant Inputs
- 0 Hz to 400 kHz clock frequency
- ESD protection exceeds 2000 V HBM per JESD22-A114 and 1000 V CDM per JESD22-C101
- Latch-up testing is done to JEDEC Standard JESD78 which exceeds 100 mA
- Three packages offered: SO20, TSSOP20 and HVQFN20



### 3. Ordering information

Table 1. Ordering information

| Type number | Topside marking | Package |  |          |
|-------------|-----------------|---------|--|----------|
|             |                 | Name    | Description  | Version  |
| PCA9544ABS  | 9544A           | HVQFN20 | plastic thermal enhanced very thin quad flat package; no leads; 20 terminals; body 5 × 5 × 0.85 mm | SOT662-1 |
| PCA9544AD   | PCA9544AD       | SO20    | plastic small outline package; 20 leads; body width 7.5 mm   | SOT163-1 |
| PCA9544APW  | PA9544A         | TSSOP20 | plastic thin shrink small outline package; 20 leads; body width 4.4 mm                             | SOT360-1 |

#### 3.1 Ordering options

Table 2. Ordering options

| Type number | Orderable part number | Package | Packing method                                  | Minimum order quantity | Temperature range                   |
|-------------|-----------------------|---------|---|------------------------|-------------------------------------|
| PCA9544ABS  | PCA9544ABS,118        | HVQFN20 | Reel 13" Q1/T1<br>*Standard mark SMD            | 6000                   | T <sub>amb</sub> = -40 °C to +85 °C |
| PCA9544AD   | PCA9544AD,112         | SO20    | Standard marking<br>* IC's tube - DSC bulk pack | 1520                   | T <sub>amb</sub> = -40 °C to +85 °C |
|             | PCA9544AD,118         | SO20    | Reel 13" Q1/T1<br>*Standard mark SMD            | 2000                   | T <sub>amb</sub> = -40 °C to +85 °C |
| PCA9544APW  | PCA9544APW,112        | TSSOP20 | Standard marking<br>* IC's tube - DSC bulk pack | 1875                   | T <sub>amb</sub> = -40 °C to +85 °C |
|             | PCA9544APW,118        | TSSOP20 | Reel 13" Q1/T1<br>*Standard mark SMD            | 2500                   | T <sub>amb</sub> = -40 °C to +85 °C |

### 4. Block diagram

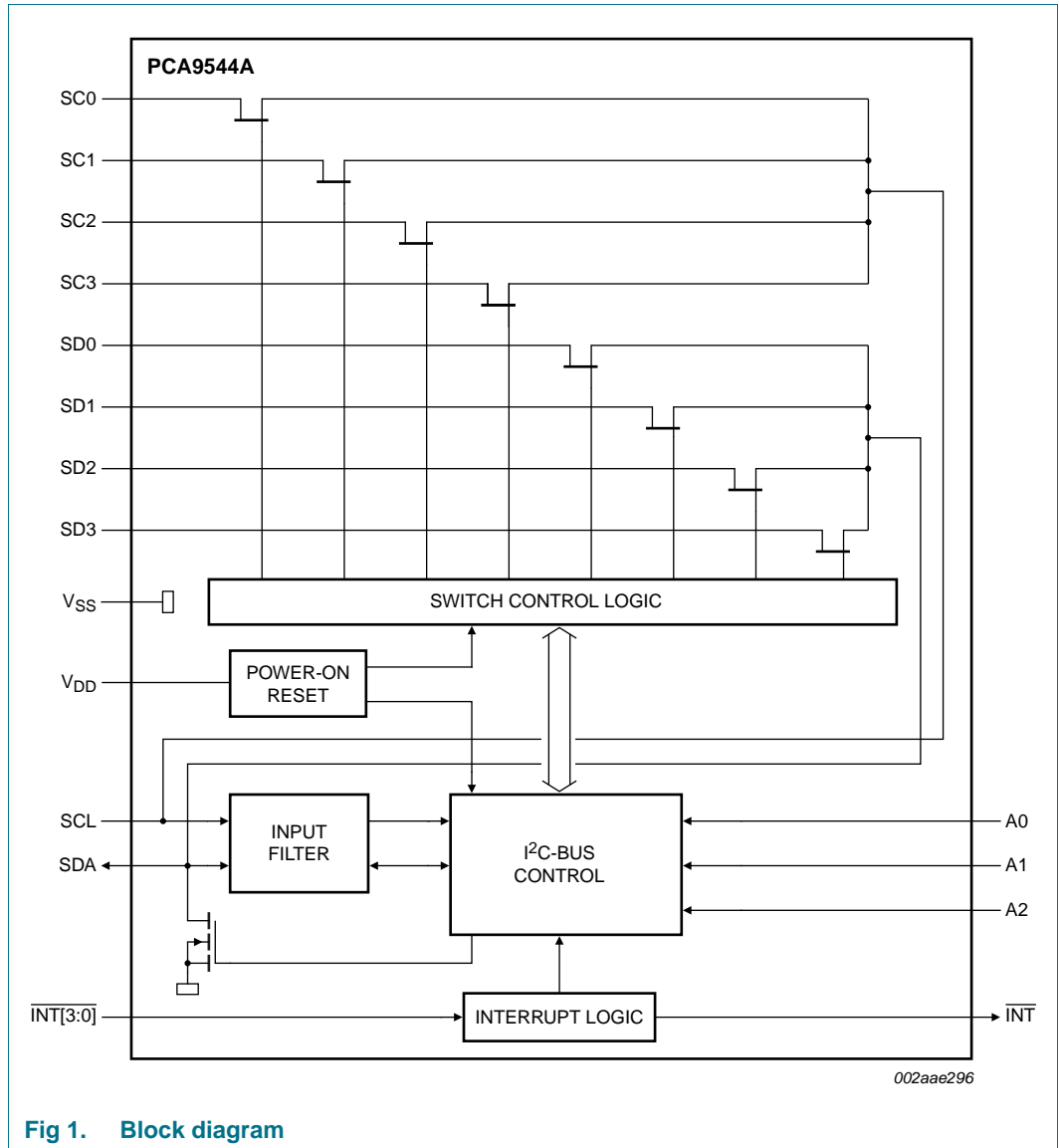
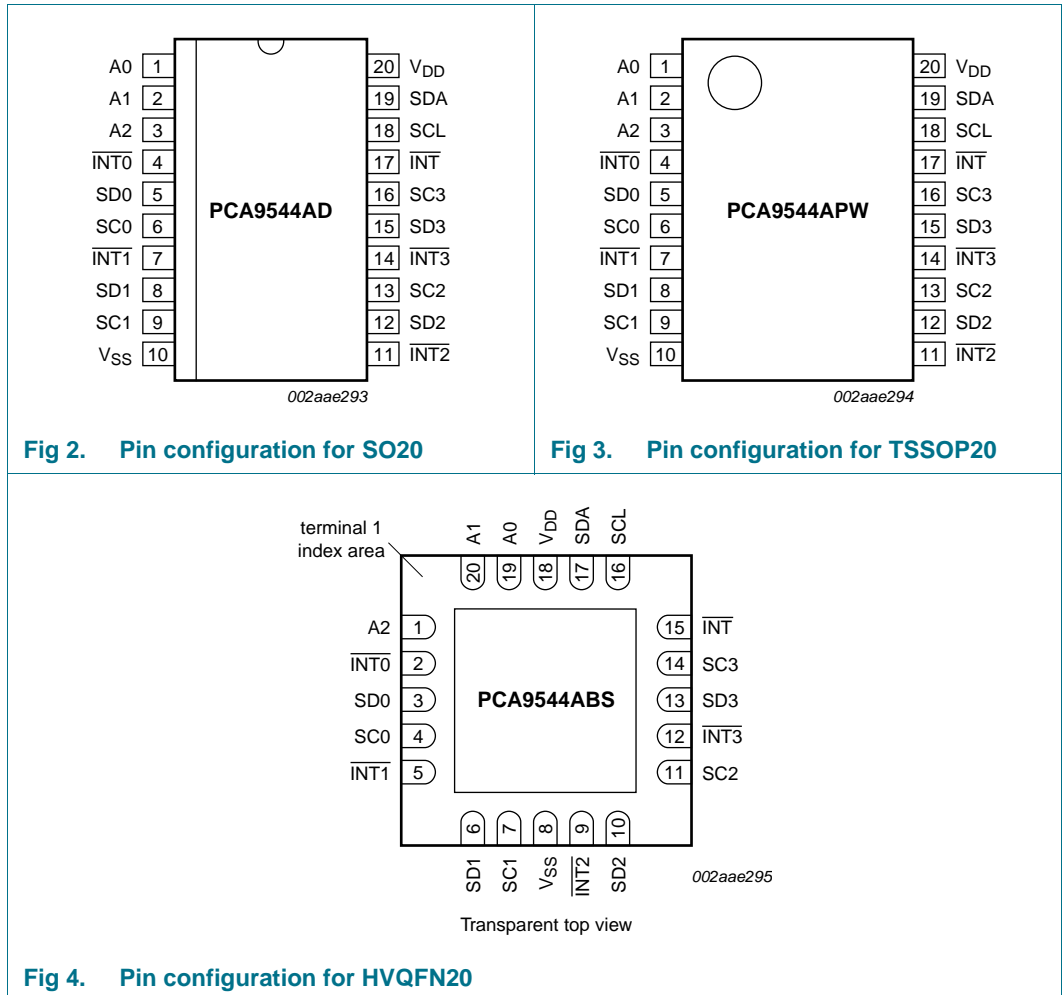


Fig 1. Block diagram

## 5. Pinning information

### 5.1 Pinning



## 5.2 Pin description

Table 3. Pin description

| Symbol                   | Pin           |                  | Description                  |
|--------------------------|---------------|------------------|------------------------------|
|                          | SO20, TSSOP20 | HVQFN20          |                              |
| A0                       | 1             | 19               | address input 0              |
| A1                       | 2             | 20               | address input 1              |
| A2                       | 3             | 1                | address input 2              |
| $\overline{\text{INT0}}$ | 4             | 2                | active LOW interrupt input 0 |
| SD0                      | 5             | 3                | serial data 0                |
| SC0                      | 6             | 4                | serial clock 0               |
| $\overline{\text{INT1}}$ | 7             | 5                | active LOW interrupt input 1 |
| SD1                      | 8             | 6                | serial data 1                |
| SC1                      | 9             | 7                | serial clock 1               |
| V <sub>SS</sub>          | 10            | 8 <sup>[1]</sup> | supply ground                |
| $\overline{\text{INT2}}$ | 11            | 9                | active LOW interrupt input 2 |
| SD2                      | 12            | 10               | serial data 2                |
| SC2                      | 13            | 11               | serial clock 2               |
| $\overline{\text{INT3}}$ | 14            | 12               | active LOW interrupt input 3 |
| SD3                      | 15            | 13               | serial data 3                |
| SC3                      | 16            | 14               | serial clock 3               |
| $\overline{\text{INT}}$  | 17            | 15               | active LOW interrupt output  |
| SCL                      | 18            | 16               | serial clock line            |
| SDA                      | 19            | 17               | serial data line             |
| V <sub>DD</sub>          | 20            | 18               | supply voltage               |

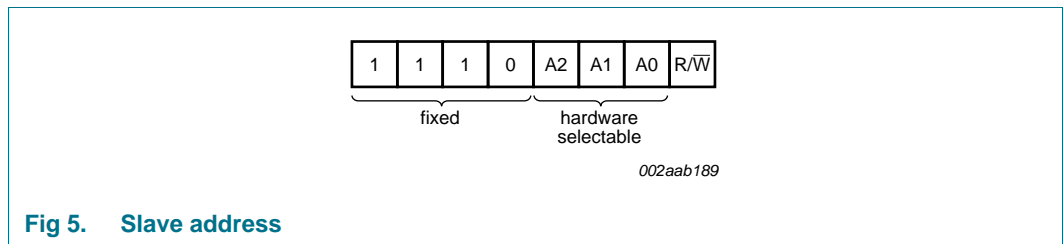
- [1] HVQFN20 package supply ground is connected to both V<sub>SS</sub> pin and exposed center pad. V<sub>SS</sub> pin must be connected to supply ground for proper device operation. For enhanced thermal, electrical, and board level performance, the exposed pad must be soldered to the board using a corresponding thermal pad on the board and for proper heat conduction through the board, thermal vias must be incorporated in the PCB in the thermal pad region.

## 6. Functional description

Refer to [Figure 1 “Block diagram”](#).

### 6.1 Device addressing

Following a START condition the bus master must output the address of the slave it is accessing. The address of the PCA9544A is shown in [Figure 5](#). To conserve power, no internal pull-up resistors are incorporated on the hardware selectable address pins and they must be pulled HIGH or LOW.

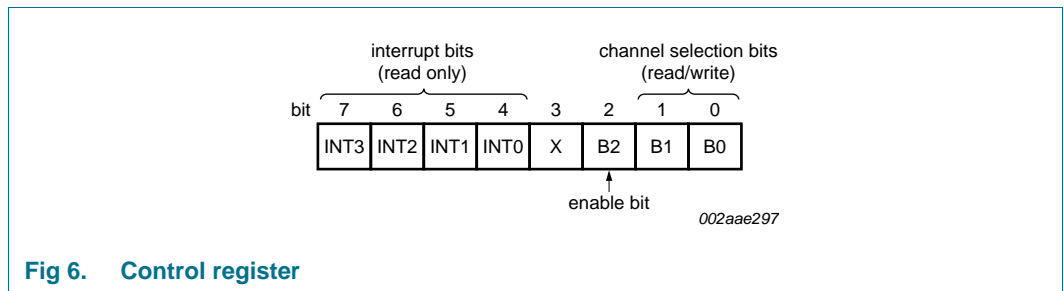


**Fig 5. Slave address**

The last bit of the slave address defines the operation to be performed. When set to logic 1 a read is selected, while a logic 0 selects a write operation.

### 6.2 Control register

Following the successful acknowledgement of the slave address, the bus master sends a byte to the PCA9544A which is stored in the Control register. If the PCA9544A receives multiple bytes, it saves the last byte received. This register can be written and read via the I<sup>2</sup>C-bus.



**Fig 6. Control register**

#### 6.2.1 Control register definition

A SCx/SDx downstream pair, or channel, is selected by the contents of the control register. This register is written after the PCA9544A has been addressed. The 3 LSBs of the control byte are used to determine which channel is to be selected. When a channel is selected, it will become active after a STOP condition has been placed on the I<sup>2</sup>C-bus. This ensures that all SCx/SDx lines are in a HIGH state when the channel is made active, so that no false conditions are generated at the time of connection.

**Table 4. Control register: Write — channel selection; Read — channel status**

| INT3 | INT2 | INT1 | INT0 | D3 | B2 | B1 | B0 | Command  |
|------|------|------|------|----|----|----|----|--|
| X    | X    | X    | X    | X  | 0  | X  | X  | no channel selected                            |
| X    | X    | X    | X    | X  | 1  | 0  | 0  | channel 0 enabled                              |
| X    | X    | X    | X    | X  | 1  | 0  | 1  | channel 1 enabled                              |
| X    | X    | X    | X    | X  | 1  | 1  | 0  | channel 2 enabled                              |
| X    | X    | X    | X    | X  | 1  | 1  | 1  | channel 3 enabled                              |
| 0    | 0    | 0    | 0    | 0  | 0  | 0  | 0  | no channel selected;<br>power-up default state |

### 6.3 Interrupt handling

The PCA9544A provides 4 interrupt inputs, one for each channel and one open-drain interrupt output. When an interrupt is generated by any device, it is detected by the PCA9544A and the interrupt output is driven LOW. The channel need not be active for detection of the interrupt. A bit is also set in the control byte. Bits 7:4 of the control byte correspond to channel 3 to channel 0 of the PCA9544A, respectively. Therefore, if an interrupt is generated by any device connected to channel 2, the state of the interrupt inputs is loaded into the control register when a read is accomplished. Likewise, an interrupt on any device connected to channel 0 would cause bit 4 of the control register to be set on the read. The master can then address the PCA9544A and read the contents of the control byte to determine which channel contains the device generating the interrupt. The master can then reconfigure the PCA9544A to select this channel, and locate the device generating the interrupt and clear it. The interrupt clears when the device originating the interrupt clears.

It should be noted that more than one device can be providing an interrupt on a channel, so it is up to the master to ensure that all devices on a channel are interrogated for an interrupt.

If the interrupt function is not required, the interrupt inputs may be used as general-purpose inputs.

If unused, interrupt inputs must be connected to V<sub>DD</sub> through a pull-up resistor.

**Table 5. Control register read — interrupt**

| INT3 | INT2 | INT1 | INT0 | D3 | B2 | B1 | B0 | Command                   |
|------|------|------|------|----|----|----|----|---------------------------|
| X    | X    | X    | 0    | X  | X  | X  | X  | no interrupt on channel 0 |
|      |      |      | 1    |    |    |    |    | interrupt on channel 0    |
| X    | X    | X    | X    | X  | X  | X  | X  | no interrupt on channel 1 |
|      |      |      |      |    |    |    |    | 1                         |
| X    | X    | X    | X    | X  | X  | X  | X  | no interrupt on channel 2 |
|      |      |      |      |    |    |    |    | 1                         |
| 0    | X    | X    | X    | X  | X  | X  | X  | no interrupt on channel 3 |
|      |      |      |      |    |    |    |    | 1                         |

**Remark:** Several interrupts can be active at the same time. For example: INT3 = 0, INT2 = 1, INT1 = 1, INT0 = 0, means that there is no interrupt on channel 0 and channel 3, and there is an interrupt on channel 1 and on channel 2.

**6.4 Power-on reset**

When power is applied to  $V_{DD}$ , an internal Power-On Reset (POR) holds the PCA9544A in a reset condition until  $V_{DD}$  has reached  $V_{POR}$ . At this point, the reset condition is released and the PCA9544A registers and I<sup>2</sup>C-bus state machine are initialized to their default states (all zeroes), causing all the channels to be deselected. Thereafter,  $V_{DD}$  must be lowered below 0.2 V for at least 5  $\mu$ s in order to reset the device.

**6.5 Voltage translation**

The pass gate transistors of the PCA9544A are constructed such that the  $V_{DD}$  voltage can be used to limit the maximum voltage that is passed from one I<sup>2</sup>C-bus to another.

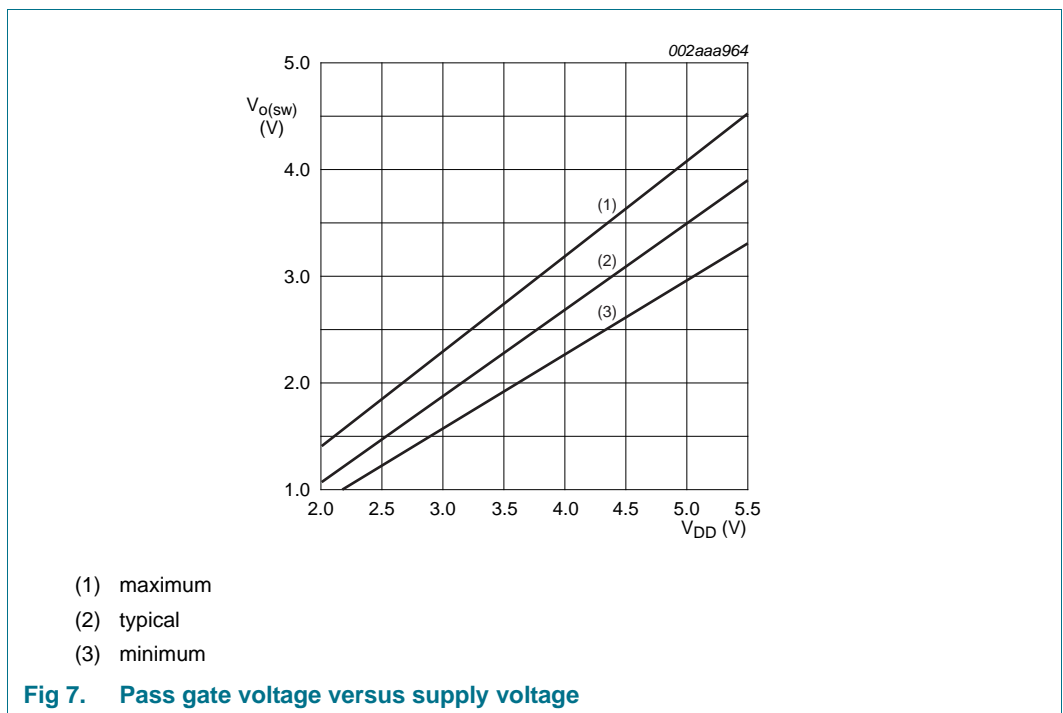


Figure 7 shows the voltage characteristics of the pass gate transistors (note that the graph was generated using the data specified in Section 12 “Dynamic characteristics” of this data sheet). In order for the PCA9544A to act as a voltage translator, the  $V_{o(sw)}$  voltage should be equal to, or lower than the lowest bus voltage. For example, if the main bus was running at 5 V, and the downstream buses were 3.3 V and 2.7 V, then  $V_{o(sw)}$  should be equal to or below 2.7 V to effectively clamp the downstream bus voltages. Looking at Figure 7, we see that  $V_{o(sw)(max)}$  is at 2.7 V when the PCA9544A supply voltage is 3.5 V or lower so the PCA9544A supply voltage could be set to 3.3 V. Pull-up resistors can then be used to bring the bus voltages to their appropriate levels (see Figure 14).

More Information can be found in Application Note AN262, PCA954X family of I<sup>2</sup>C/SMBus multiplexers and switches.



## 7. Characteristics of the I<sup>2</sup>C-bus

The I<sup>2</sup>C-bus is for 2-way, 2-line communication between different ICs or modules. The two lines are a serial data line (SDA) and a serial clock line (SCL). Both lines must be connected to a positive supply via a pull-up resistor when connected to the output stages of a device. Data transfer may be initiated only when the bus is not busy.

### 7.1 Bit transfer

One data bit is transferred during each clock pulse. The data on the SDA line must remain stable during the HIGH period of the clock pulse as changes in the data line at this time will be interpreted as control signals (see [Figure 8](#)).



Fig 8. Bit transfer

### 7.2 START and STOP conditions

Both data and clock lines remain HIGH when the bus is not busy. A HIGH-to-LOW transition of the data line while the clock is HIGH is defined as the START condition (S). A LOW-to-HIGH transition of the data line while the clock is HIGH is defined as the STOP condition (P) (see [Figure 9](#)).

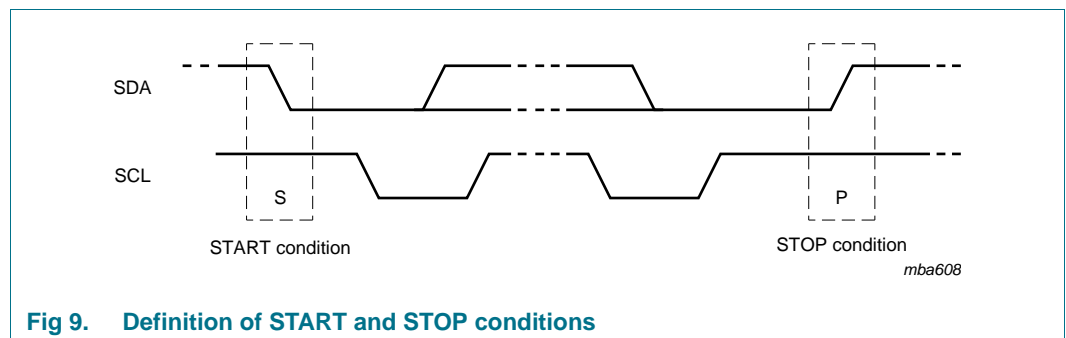


Fig 9. Definition of START and STOP conditions

### 7.3 System configuration

A device generating a message is a 'transmitter', a device receiving is the 'receiver'. The device that controls the message is the 'master' and the devices which are controlled by the master are the 'slaves' (see [Figure 10](#)).

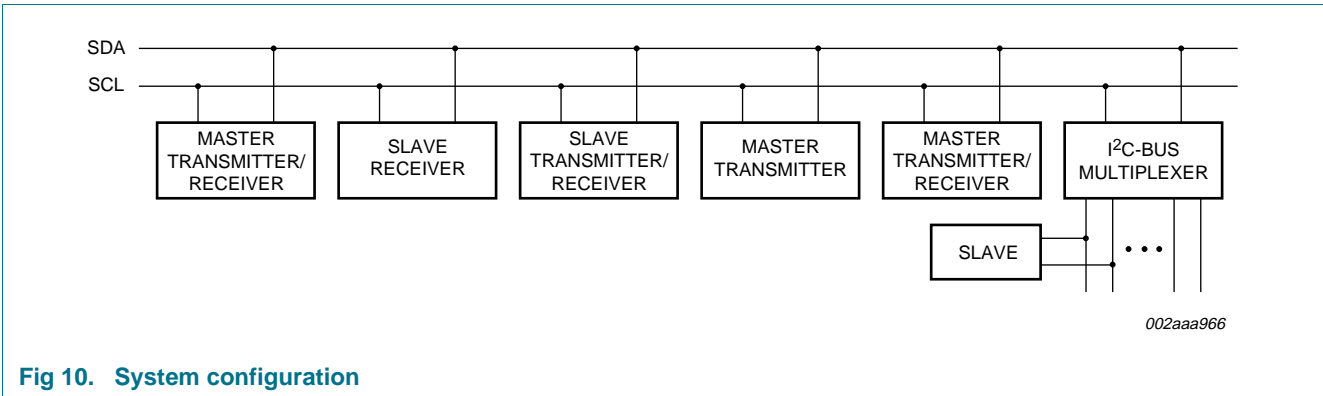


Fig 10. System configuration

### 7.4 Acknowledge

The number of data bytes transferred between the START and the STOP conditions from transmitter to receiver is not limited. Each byte of 8 bits is followed by one acknowledge bit. The acknowledge bit is a HIGH level put on the bus by the transmitter, whereas the master generates an extra acknowledge related clock pulse.

A slave receiver which is addressed must generate an acknowledge after the reception of each byte. Also, a master must generate an acknowledge after the reception of each byte that has been clocked out of the slave transmitter. The device that acknowledges has to pull down the SDA line during the acknowledge clock pulse so that the SDA line is stable LOW during the HIGH period of the acknowledge related clock pulse; set-up and hold times must be taken into account.

A master receiver must signal an end of data to the transmitter by not generating an acknowledge on the last byte that has been clocked out of the slave. In this event, the transmitter must leave the data line HIGH to enable the master to generate a STOP condition.

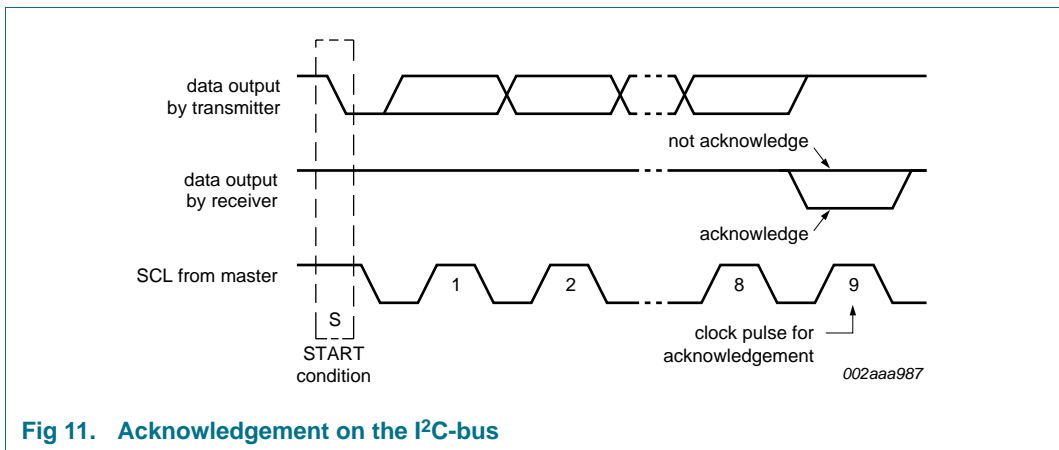
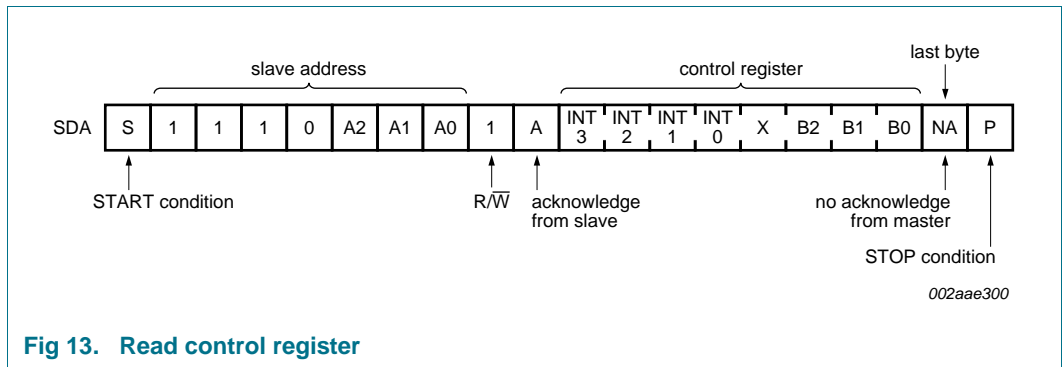
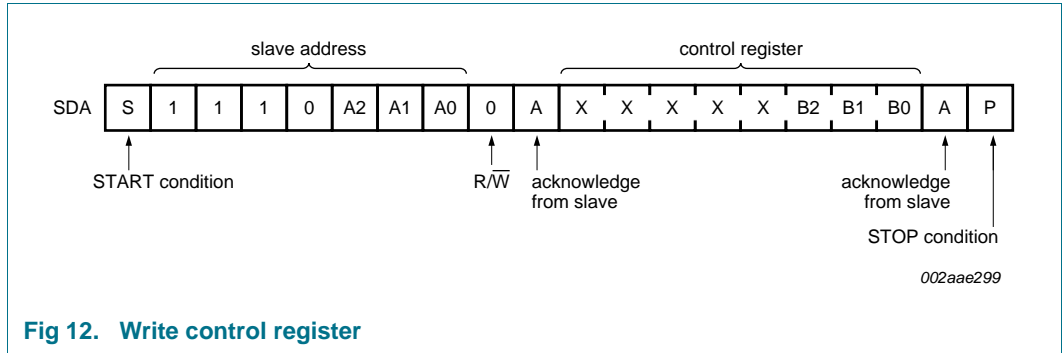
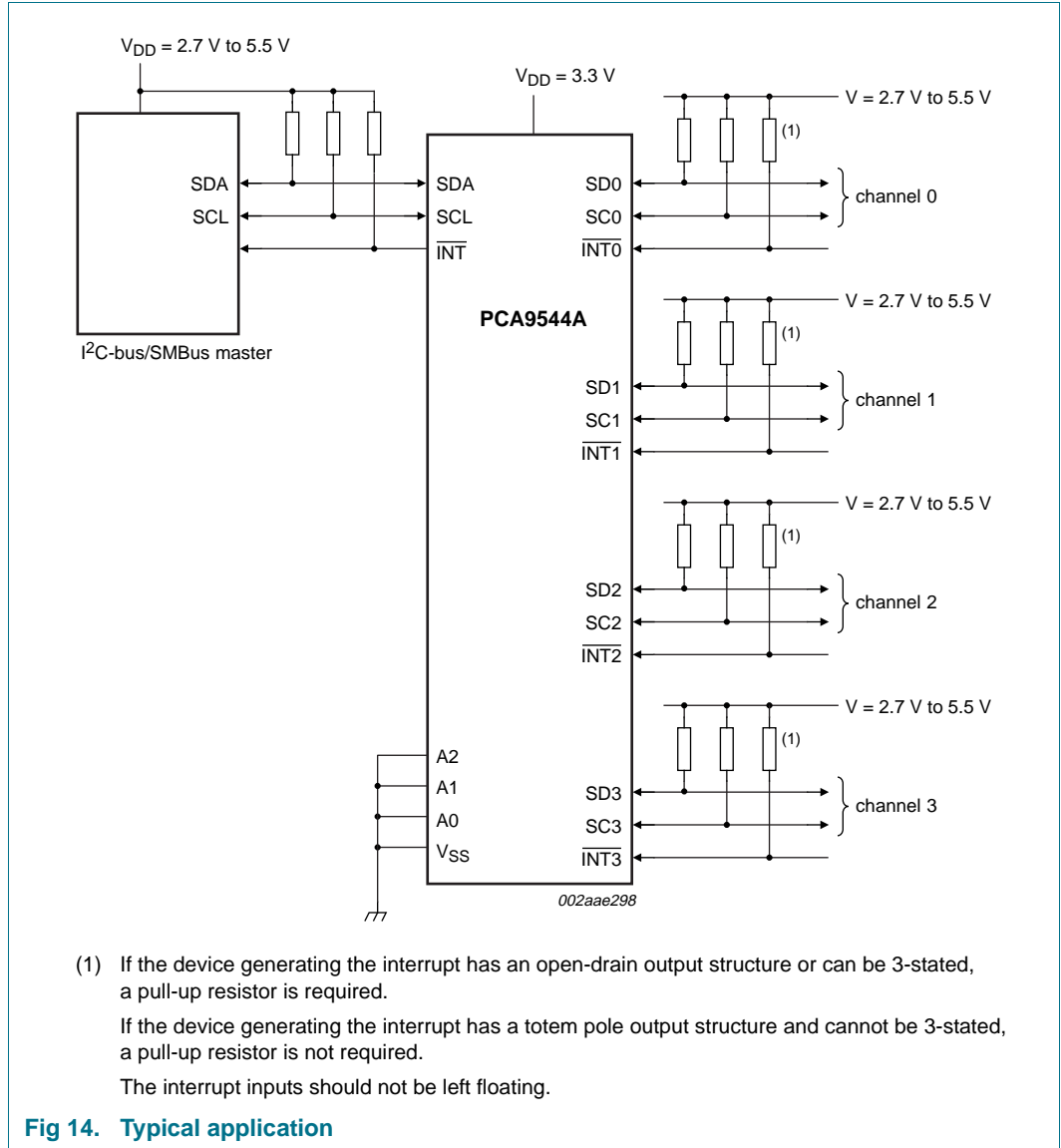


Fig 11. Acknowledgement on the I<sup>2</sup>C-bus

7.5 Bus transactions



8. Application design-in information



## 9. Limiting values

**Table 6. Limiting values**

In accordance with the Absolute Maximum Rating System (IEC 60134).  
Voltages are referenced to ground ( $V_{SS} = 0$  V).<sup>[1]</sup>

| Symbol       | Parameter                    | Conditions | Min  | Max  | Unit |
|--------------|------------------------------|------------|------|------|------|
| $V_{DD}$     | supply voltage               |            | -0.5 | +7.0 | V    |
| $V_I$        | input voltage                |            | -0.5 | +7.0 | V    |
| $I_I$        | input current                |            | -    | ±20  | mA   |
| $I_O$        | output current               |            | -    | ±25  | mA   |
| $I_{DD}$     | supply current               |            | -    | ±100 | mA   |
| $I_{SS}$     | ground supply current        |            | -    | ±100 | mA   |
| $P_{tot}$    | total power dissipation      |            | -    | 400  | mW   |
| $T_{j(max)}$ | maximum junction temperature | [1]        | -    | 125  | °C   |
| $T_{stg}$    | storage temperature          |            | -60  | +150 | °C   |
| $T_{amb}$    | ambient temperature          | operating  | -40  | +85  | °C   |

[1] The performance capability of a high-performance integrated circuit in conjunction with its thermal environment can create junction temperatures which are detrimental to reliability. The maximum junction temperature of this integrated circuit should not exceed 125 °C.

## 10. Thermal characteristics

**Table 7. Thermal characteristics**

| Symbol        | Parameter                                   | Conditions      | Typ | Unit |
|---------------|---|-----------------|-----|------|
| $R_{th(j-a)}$ | thermal resistance from junction to ambient | HVQFN20 package | 32  | °C/W |
|               |   | SO20 package    | 90  | °C/W |
|               |   | TSSOP20 package | 146 | °C/W |

## 11. Static characteristics

**Table 8. Static characteristics at  $V_{DD} = 2.3\text{ V to }3.6\text{ V}$** 
 $V_{SS} = 0\text{ V}$ ;  $T_{amb} = -40\text{ °C to }+85\text{ °C}$ ; unless otherwise specified. See [Table 9](#) for  $V_{DD} = 4.5\text{ V to }5.5\text{ V}$ .<sup>[1]</sup>

| Symbol                                      | Parameter                 | Conditions   | Min          | Typ | Max           | Unit          |
|---|---------------------------|--|--------------|-----|---------------|---------------|
| <b>Supply</b>                               |                           |  |              |     |               |               |
| $V_{DD}$                                    | supply voltage            |  | 2.3          | -   | 3.6           | V             |
| $I_{DD}$                                    | supply current            | operating mode; $V_{DD} = 3.6\text{ V}$ ;<br>no load; $V_I = V_{DD}$ or $V_{SS}$ ;<br>$f_{SCL} = 100\text{ kHz}$ | -            | 10  | 30            | $\mu\text{A}$ |
| $I_{stb}$                                   | standby current           | standby mode; $V_{DD} = 3.6\text{ V}$ ; no load;<br>$V_I = V_{DD}$ or $V_{SS}$ ; $f_{SCL} = 0\text{ kHz}$        | -            | 0.1 | 1             | $\mu\text{A}$ |
| $V_{POR}$                                   | power-on reset voltage    | no load; $V_I = V_{DD}$ or $V_{SS}$  | [2]          | 1.5 | 2.1           | V             |
| <b>Input SCL; input/output SDA</b>          |                           |  |              |     |               |               |
| $V_{IL}$                                    | LOW-level input voltage   |  | -0.5         | -   | +0.3 $V_{DD}$ | V             |
| $V_{IH}$                                    | HIGH-level input voltage  |  | 0.7 $V_{DD}$ | -   | 6             | V             |
| $I_{OL}$                                    | LOW-level output current  | $V_{OL} = 0.4\text{ V}$  | 3            | 7   | -             | mA            |
|   |                           | $V_{OL} = 0.6\text{ V}$  | 6            | 10  | -             | mA            |
| $I_L$                                       | leakage current           | $V_I = V_{DD}$ or $V_{SS}$   | -1           | -   | +1            | $\mu\text{A}$ |
| $C_i$                                       | input capacitance         | $V_I = V_{SS}$   | -            | 10  | 13            | pF            |
| <b>Select inputs A0 to A2, INT0 to INT3</b> |                           |  |              |     |               |               |
| $V_{IL}$                                    | LOW-level input voltage   |  | -0.5         | -   | +0.3 $V_{DD}$ | V             |
| $V_{IH}$                                    | HIGH-level input voltage  |  | 0.7 $V_{DD}$ | -   | 6             | V             |
| $I_{LI}$                                    | input leakage current     | $V_I = V_{DD}$ or $V_{SS}$   | -1           | -   | +1            | $\mu\text{A}$ |
| $C_i$                                       | input capacitance         | $V_I = V_{SS}$   | -            | 1.6 | 3             | pF            |
| <b>Pass gate</b>                            |                           |  |              |     |               |               |
| $R_{on}$                                    | ON-state resistance       | $V_{DD} = 3.0\text{ V to }3.6\text{ V}$ ; $V_O = 0.4\text{ V}$ ;<br>$I_O = 15\text{ mA}$                         | 5            | 11  | 30            | $\Omega$      |
|   |                           | $V_{DD} = 2.3\text{ V to }2.7\text{ V}$ ; $V_O = 0.4\text{ V}$ ;<br>$I_O = 10\text{ mA}$                         | 7            | 16  | 55            | $\Omega$      |
| $V_{o(sw)}$                                 | switch output voltage     | $V_{i(sw)} = V_{DD} = 3.3\text{ V}$ ; $I_{o(sw)} = -100\text{ }\mu\text{A}$                                      | -            | 1.9 | -             | V             |
|   |                           | $V_{i(sw)} = V_{DD} = 3.0\text{ V to }3.6\text{ V}$ ;<br>$I_{o(sw)} = -100\text{ }\mu\text{A}$                   | 1.6          | -   | 2.8           | V             |
|   |                           | $V_{i(sw)} = V_{DD} = 2.5\text{ V}$ ; $I_{o(sw)} = -100\text{ }\mu\text{A}$                                      | -            | 1.5 | -             | V             |
|   |                           | $V_{i(sw)} = V_{DD} = 2.3\text{ V to }2.7\text{ V}$ ;<br>$I_{o(sw)} = -100\text{ }\mu\text{A}$                   | 1.1          | -   | 2.0           | V             |
| $I_L$                                       | leakage current           | $V_I = V_{DD}$ or $V_{SS}$   | -1           | -   | +1            | $\mu\text{A}$ |
| $C_{io}$                                    | input/output capacitance  | $V_I = V_{SS}$   | -            | 3   | 5             | pF            |
| <b>INT output</b>                           |                           |  |              |     |               |               |
| $I_{OL}$                                    | LOW-level output current  | $V_{OL} = 0.4\text{ V}$  | 3            | 7   | -             | mA            |
| $I_{OH}$                                    | HIGH-level output current |  | -            | -   | +10           | $\mu\text{A}$ |

[1] For operation between published voltage ranges, refer to worst case parameter in both ranges.

[2] In order to reset part,  $V_{DD}$  must be lowered to 0.2 V for at least 5  $\mu\text{s}$ .

**Table 9. Static characteristics at V<sub>DD</sub> = 4.5 V to 5.5 V**V<sub>SS</sub> = 0 V; T<sub>amb</sub> = -40 °C to +85 °C; unless otherwise specified. See [Table 8](#) for V<sub>DD</sub> = 2.3 V to 3.6 V.<sup>[1]</sup>

| Symbol                                      | Parameter                 | Conditions   | Min                | Typ | Max                 | Unit |
|---|---------------------------|--|--------------------|-----|---------------------|------|
| <b>Supply</b>                               |                           |  |                    |     |                     |      |
| V <sub>DD</sub>                             | supply voltage            |  | 4.5                | -   | 5.5                 | V    |
| I <sub>DD</sub>                             | supply current            | operating mode; V <sub>DD</sub> = 5.5 V;<br>no load; V <sub>I</sub> = V <sub>DD</sub> or V <sub>SS</sub> ;<br>f <sub>SCL</sub> = 100 kHz | -                  | 25  | 100                 | μA   |
| I <sub>stb</sub>                            | standby current           | standby mode; V <sub>DD</sub> = 5.5 V; no load;<br>V <sub>I</sub> = V <sub>DD</sub> or V <sub>SS</sub> ; f <sub>SCL</sub> = 0 kHz        | -                  | 0.3 | 1                   | μA   |
| V <sub>POR</sub>                            | power-on reset voltage    | no load; V <sub>I</sub> = V <sub>DD</sub> or V <sub>SS</sub>   | [2]                | 1.7 | 2.1                 | V    |
| <b>Input SCL; input/output SDA</b>          |                           |  |                    |     |                     |      |
| V <sub>IL</sub>                             | LOW-level input voltage   |  | -0.5               | -   | +0.3V <sub>DD</sub> | V    |
| V <sub>IH</sub>                             | HIGH-level input voltage  |  | 0.7V <sub>DD</sub> | -   | 6                   | V    |
| I <sub>OL</sub>                             | LOW-level output current  | V <sub>OL</sub> = 0.4 V  | 3                  | -   | -                   | mA   |
|   |                           | V <sub>OL</sub> = 0.6 V  | 6                  | -   | -                   | mA   |
| I <sub>L</sub>                              | leakage current           | V <sub>I</sub> = V <sub>DD</sub> or V <sub>SS</sub>  | -1                 | -   | +1                  | μA   |
| C <sub>i</sub>                              | input capacitance         | V <sub>I</sub> = V <sub>SS</sub>   | -                  | 12  | 13                  | pF   |
| <b>Select inputs A0 to A2, INT0 to INT3</b> |                           |  |                    |     |                     |      |
| V <sub>IL</sub>                             | LOW-level input voltage   |  | -0.5               | -   | +0.3V <sub>DD</sub> | V    |
| V <sub>IH</sub>                             | HIGH-level input voltage  |  | 0.7V <sub>DD</sub> | -   | 6                   | V    |
| I <sub>LI</sub>                             | input leakage current     | pin at V <sub>DD</sub> or V <sub>SS</sub>  | -1                 | -   | +1                  | μA   |
| C <sub>i</sub>                              | input capacitance         | V <sub>I</sub> = V <sub>SS</sub>   | -                  | 2   | 5                   | pF   |
| <b>Pass gate</b>                            |                           |  |                    |     |                     |      |
| R <sub>on</sub>                             | ON-state resistance       | V <sub>DD</sub> = 4.5 V to 5.5 V; V <sub>O</sub> = 0.4 V;<br>I <sub>O</sub> = 15 mA  | 4                  | 9   | 24                  | Ω    |
| V <sub>o(sw)</sub>                          | switch output voltage     | V <sub>i(sw)</sub> = V <sub>DD</sub> = 5.0 V; I <sub>o(sw)</sub> = -100 μA   | -                  | 3.6 | -                   | V    |
|   |                           | V <sub>i(sw)</sub> = V <sub>DD</sub> = 4.5 V to 5.5 V;<br>I <sub>o(sw)</sub> = -100 μA   | 2.6                | -   | 4.5                 | V    |
| I <sub>L</sub>                              | leakage current           | V <sub>I</sub> = V <sub>DD</sub> or V <sub>SS</sub>  | -1                 | -   | +1                  | μA   |
| C <sub>io</sub>                             | input/output capacitance  | V <sub>I</sub> = V <sub>SS</sub>   | -                  | 3   | 5                   | pF   |
| <b>INT output</b>                           |                           |  |                    |     |                     |      |
| I <sub>OL</sub>                             | LOW-level output current  | V <sub>OL</sub> = 0.4 V  | 3                  | -   | -                   | mA   |
| I <sub>OH</sub>                             | HIGH-level output current |  | -                  | -   | +10                 | μA   |

[1] For operation between published voltage ranges, refer to worst case parameter in both ranges.

[2] In order to reset part, V<sub>DD</sub> must be lowered to 0.2 V for at least 5 μs.

## 12. Dynamic characteristics

Table 10. Dynamic characteristics

| Symbol                     | Parameter  | Conditions                        | Standard-mode I <sup>2</sup> C-bus |                    | Fast-mode I <sup>2</sup> C-bus        |                    | Unit |    |
|----------------------------|--|-----------------------------------|------------------------------------|--------------------|---------------------------------------|--------------------|------|----|
|                            |  |                                   | Min                                | Max                | Min                                   | Max                |      |    |
| t <sub>PD</sub>            | propagation delay  | from SDA to SDx,<br>or SCL to SCx | -                                  | 0.3 <sup>[1]</sup> | -                                     | 0.3 <sup>[1]</sup> | ns   |    |
| f <sub>SCL</sub>           | SCL clock frequency  |                                   | 0                                  | 100                | 0                                     | 400                | kHz  |    |
| t <sub>BUF</sub>           | bus free time between a STOP and START condition                             |                                   | 4.7                                | -                  | 1.3                                   | -                  | μs   |    |
| t <sub>HD;STA</sub>        | hold time (repeated) START condition   | <sup>[2]</sup>                    | 4.0                                | -                  | 0.6                                   | -                  | μs   |    |
| t <sub>LOW</sub>           | LOW period of the SCL clock  |                                   | 4.7                                | -                  | 1.3                                   | -                  | μs   |    |
| t <sub>HIGH</sub>          | HIGH period of the SCL clock   |                                   | 4.0                                | -                  | 0.6                                   | -                  | μs   |    |
| t <sub>SU;STA</sub>        | set-up time for a repeated START condition                                   |                                   | 4.7                                | -                  | 0.6                                   | -                  | μs   |    |
| t <sub>SU;STO</sub>        | set-up time for STOP condition   |                                   | 4.0                                | -                  | 0.6                                   | -                  | μs   |    |
| t <sub>HD;DAT</sub>        | data hold time   |                                   | 0 <sup>[3]</sup>                   | 3.45               | 0 <sup>[3]</sup>                      | 0.9                | μs   |    |
| t <sub>SU;DAT</sub>        | data set-up time   |                                   | 250                                | -                  | 100                                   | -                  | ns   |    |
| t <sub>r</sub>             | rise time of both SDA and SCL signals  |                                   | -                                  | 1000               | 20 + 0.1C <sub>b</sub> <sup>[4]</sup> | 300                | ns   |    |
| t <sub>f</sub>             | fall time of both SDA and SCL signals  |                                   | -                                  | 300                | 20 + 0.1C <sub>b</sub> <sup>[4]</sup> | 300                | ns   |    |
| C <sub>b</sub>             | capacitive load for each bus line  |                                   | -                                  | 400                | -                                     | 400                | pF   |    |
| t <sub>SP</sub>            | pulse width of spikes that must be suppressed by the input filter            |                                   | -                                  | 50                 | -                                     | 50                 | ns   |    |
| t <sub>VD;DAT</sub>        | data valid time  | HIGH-to-LOW                       | <sup>[5]</sup>                     | -                  | 1                                     | -                  | 1    | μs |
|                            |  | LOW-to-HIGH                       | <sup>[5]</sup>                     | -                  | 0.6                                   | -                  | 0.6  | μs |
| t <sub>VD;ACK</sub>        | data valid acknowledge time  |                                   | -                                  | 1                  | -                                     | 1                  | μs   |    |
| <b>INT</b>                 |  |                                   |                                    |                    |                                       |                    |      |    |
| t <sub>v(INTnN-INTN)</sub> | valid time from $\overline{\text{INTn}}$ to $\overline{\text{INT}}$ signal   | <sup>[5]</sup>                    | -                                  | 4                  | -                                     | 4                  | μs   |    |
| t <sub>d(INTnN-INTN)</sub> | delay time from $\overline{\text{INTn}}$ to $\overline{\text{INT}}$ inactive | <sup>[5]</sup>                    | -                                  | 2                  | -                                     | 2                  | μs   |    |
| t <sub>w(rej)L</sub>       | LOW-level rejection time   | $\overline{\text{INTn}}$ inputs   | <sup>[5]</sup>                     | 1                  | -                                     | 1                  | μs   |    |
| t <sub>w(rej)H</sub>       | HIGH-level rejection time  | $\overline{\text{INTn}}$ inputs   | <sup>[5]</sup>                     | 0.5                | -                                     | 0.5                | μs   |    |

[1] Pass gate propagation delay is calculated from the 20 Ω typical R<sub>on</sub> and the 15 pF load capacitance.

[2] After this period, the first clock pulse is generated.

[3] A device must internally provide a hold time of at least 300 ns for the SDA signal (referred to the V<sub>IH(min)</sub> of the SCL signal) in order to bridge the undefined region of the falling edge of SCL.

[4] C<sub>b</sub> = total capacitance of one bus line in pF.

[5] Measurements taken with 1 kΩ pull-up resistor and 50 pF load.



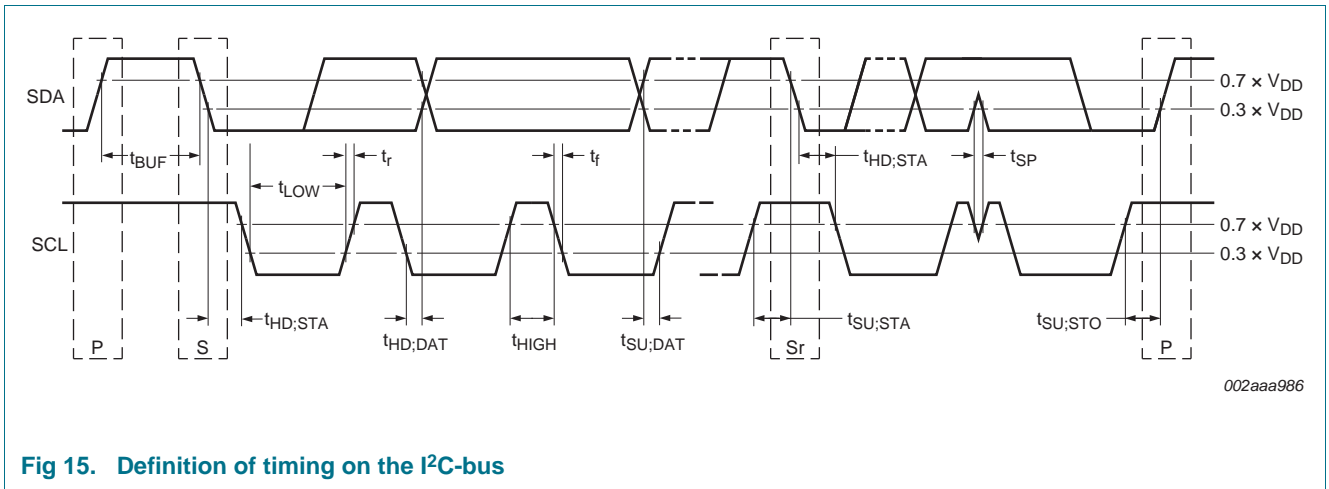


Fig 15. Definition of timing on the I<sup>2</sup>C-bus

13. Package outline

SO20: plastic small outline package; 20 leads; body width 7.5 mm

SOT163-1

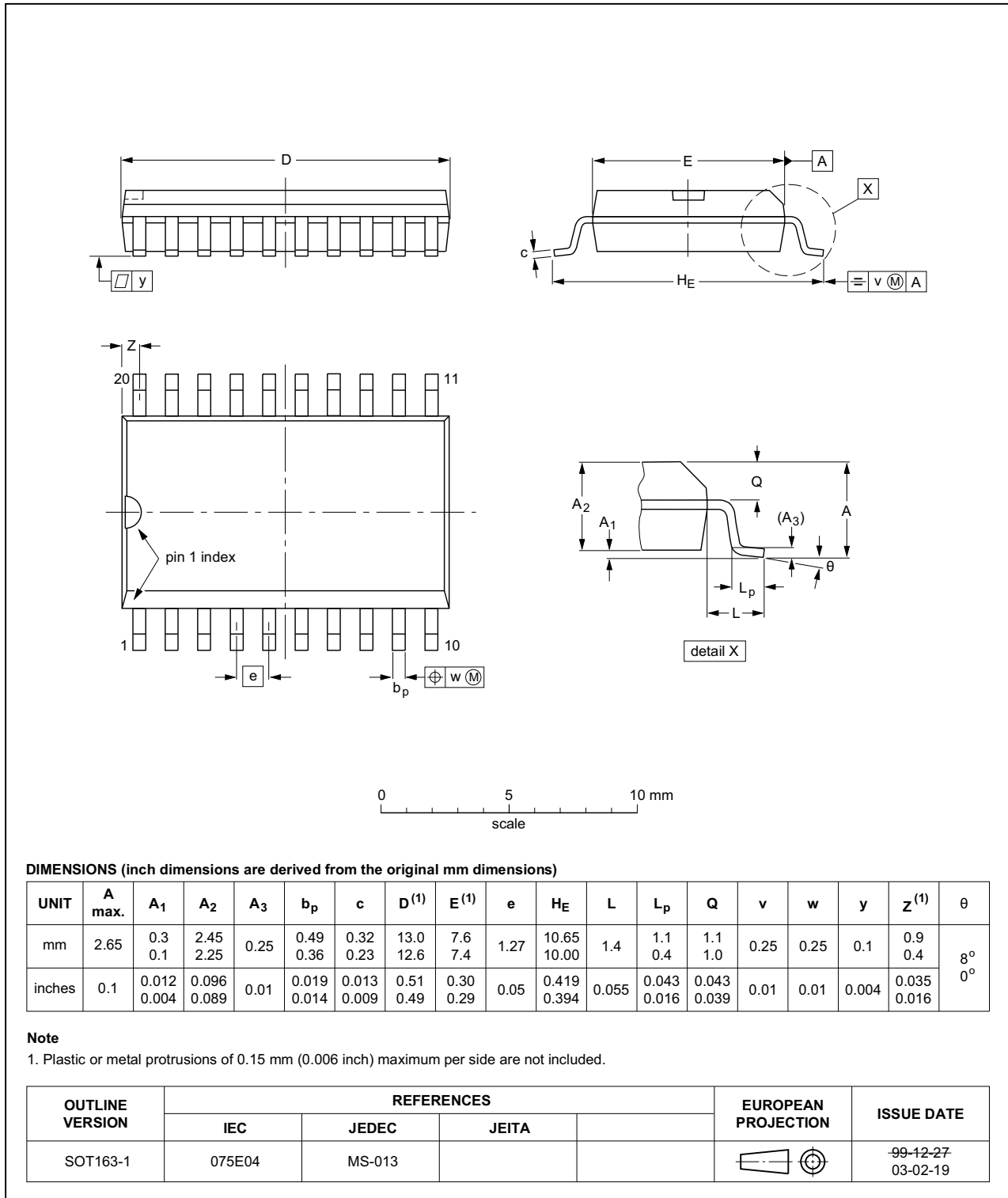


Fig 16. Package outline SOT163-1 (SO20)

TSSOP20: plastic thin shrink small outline package; 20 leads; body width 4.4 mm

SOT360-1

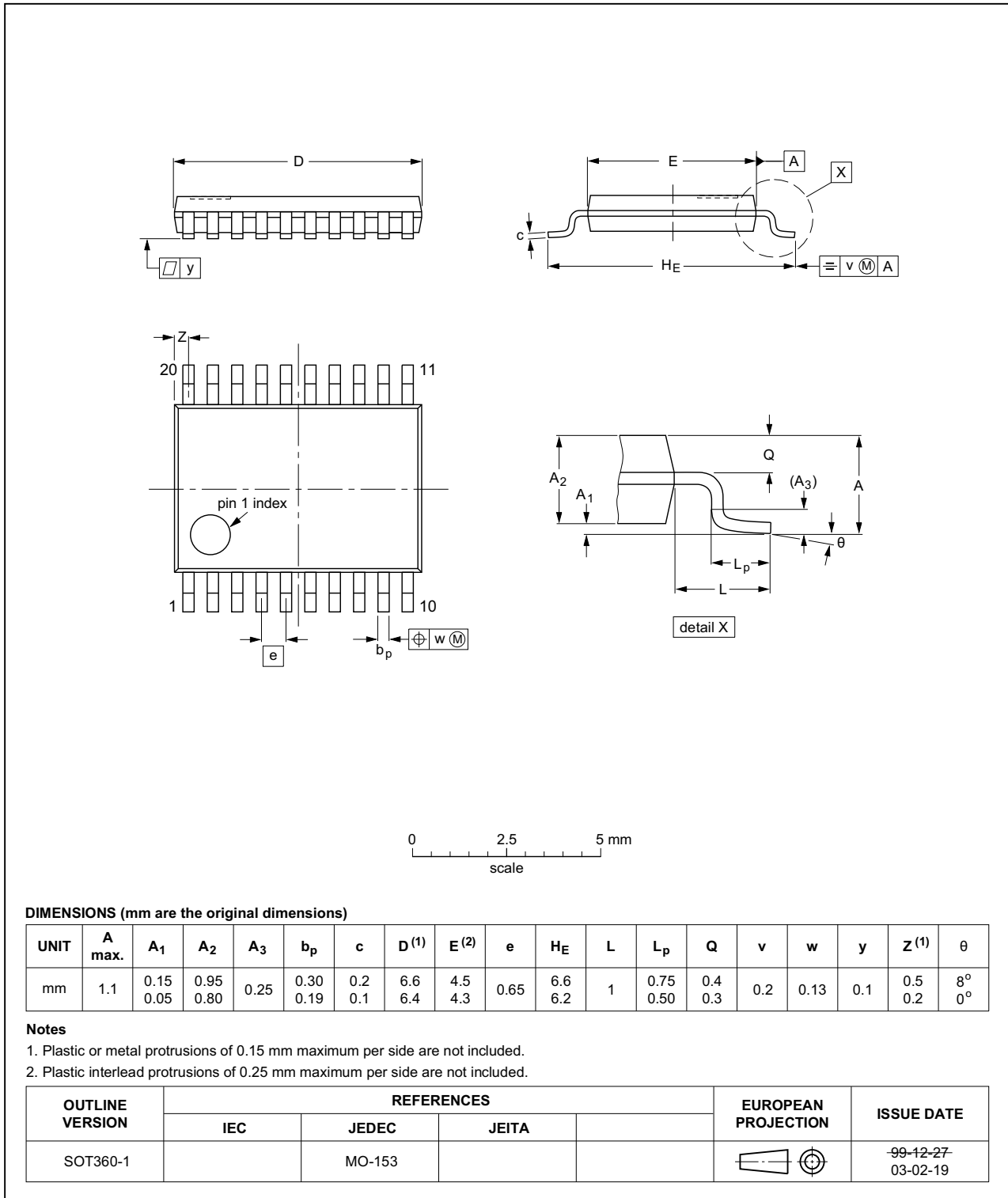


Fig 17. Package outline SOT360-1 (TSSOP20)

HVQFN20: plastic thermal enhanced very thin quad flat package; no leads;  
20 terminals; body 5 x 5 x 0.85 mm

SOT662-1

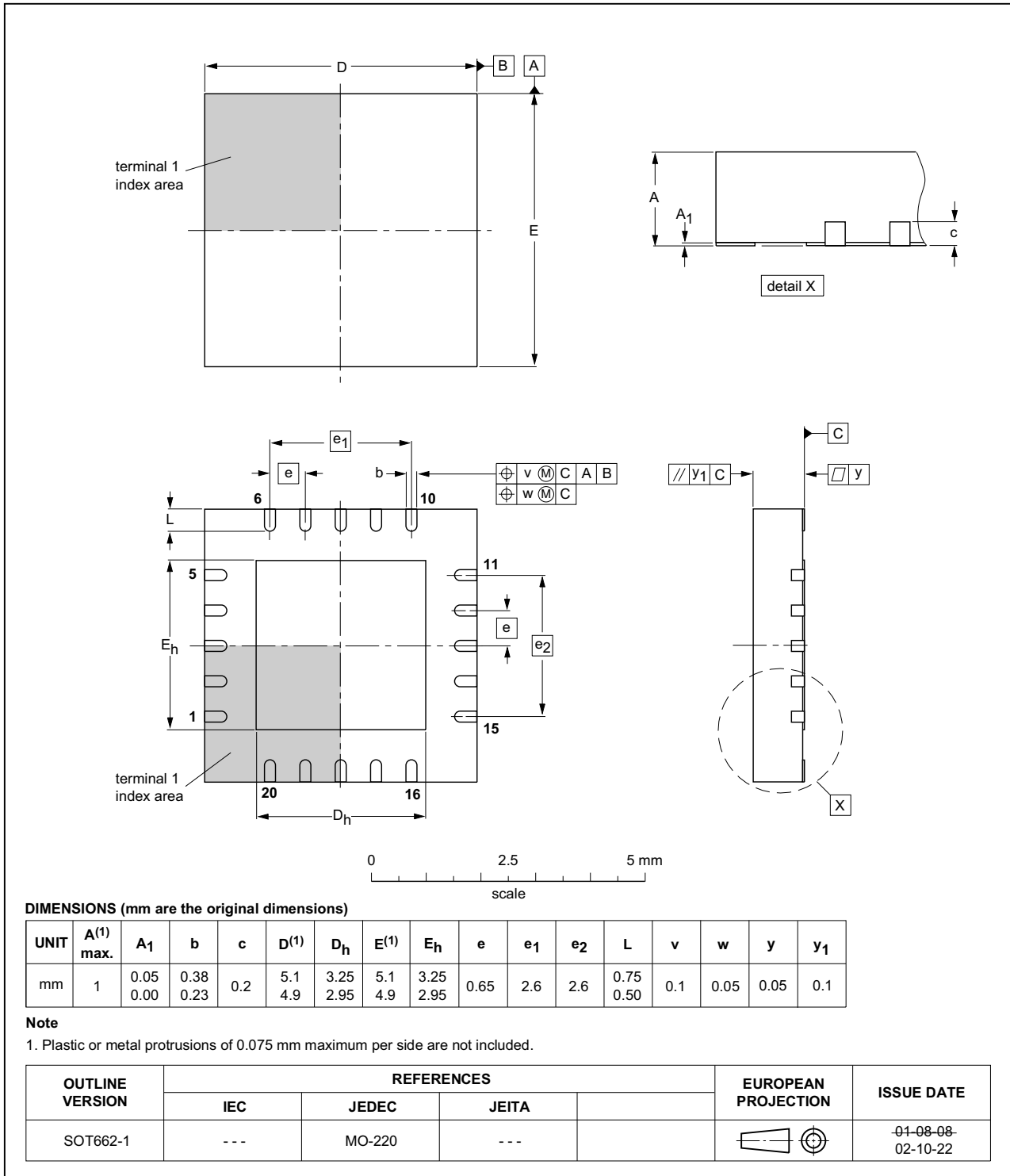


Fig 18. Package outline SOT662-1 (HVQFN20)

## 14. Soldering of SMD packages

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note AN10365 “Surface mount reflow soldering description”.

### 14.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

### 14.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- Board specifications, including the board finish, solder masks and vias
- Package footprints, including solder thieves and orientation
- The moisture sensitivity level of the packages
- Package placement
- Inspection and repair
- Lead-free soldering versus SnPb soldering

### 14.3 Wave soldering

Key characteristics in wave soldering are:

- Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- Solder bath specifications, including temperature and impurities

### 14.4 Reflow soldering

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see [Figure 19](#)) than a SnPb process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with [Table 11](#) and [12](#)

**Table 11. SnPb eutectic process (from J-STD-020D)**

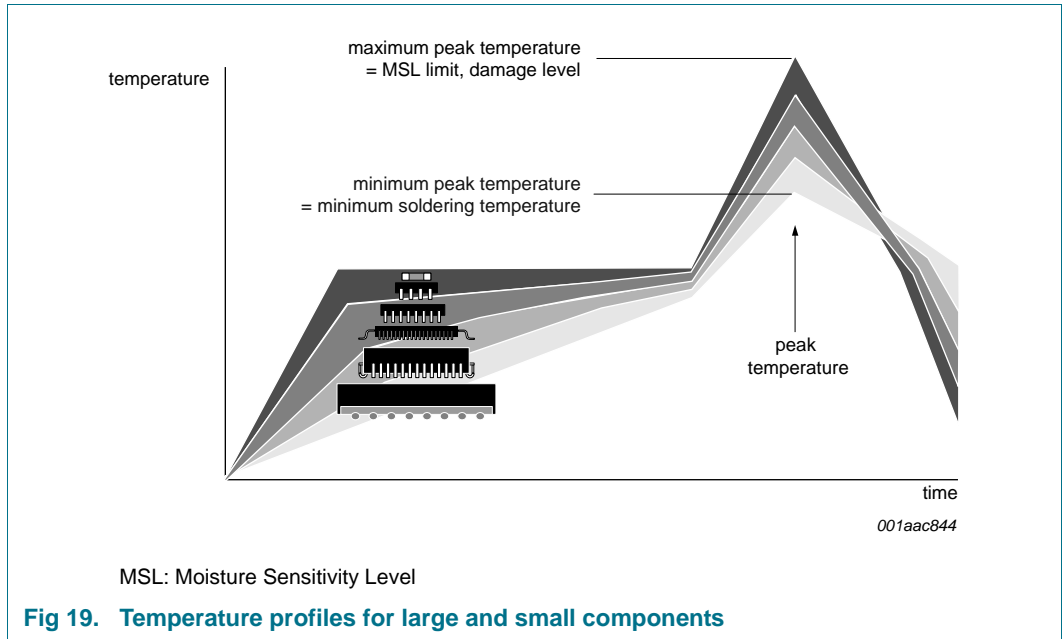
| Package thickness (mm) | Package reflow temperature (°C) |       |
|------------------------|---------------------------------|-------|
|                        | Volume (mm <sup>3</sup> )       |       |
|                        | < 350                           | ≥ 350 |
| < 2.5                  | 235                             | 220   |
| ≥ 2.5                  | 220                             | 220   |

**Table 12. Lead-free process (from J-STD-020D)**

| Package thickness (mm) | Package reflow temperature (°C) |             |        |
|------------------------|---------------------------------|-------------|--------|
|                        | Volume (mm <sup>3</sup> )       |             |        |
|                        | < 350                           | 350 to 2000 | > 2000 |
| < 1.6                  | 260                             | 260         | 260    |
| 1.6 to 2.5             | 260                             | 250         | 245    |
| > 2.5                  | 250                             | 245         | 245    |

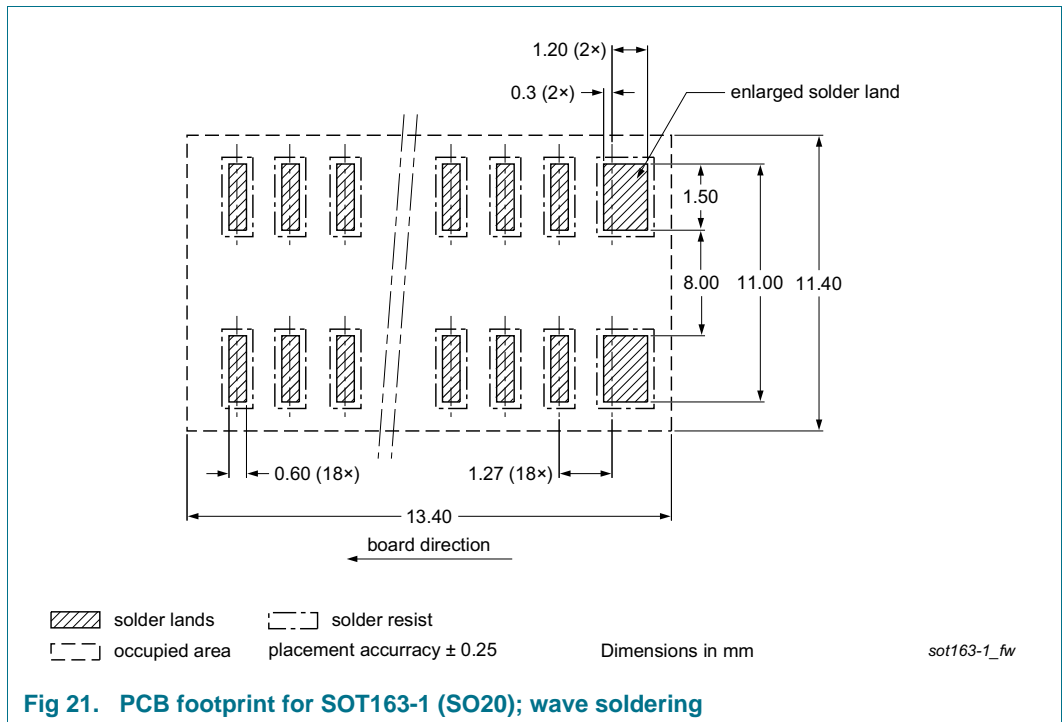
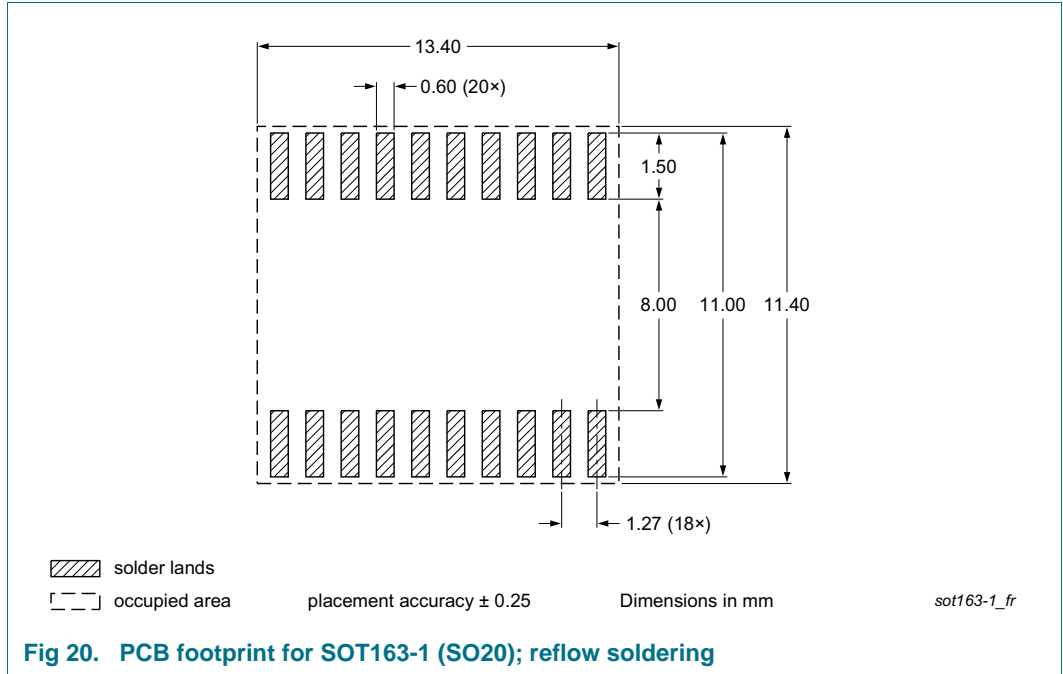
Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see [Figure 19](#).



For further information on temperature profiles, refer to Application Note AN10365 “Surface mount reflow soldering description”.

15. Soldering: PCB footprints





Footprint information for reflow soldering of TSSOP20 package

SOT360-1

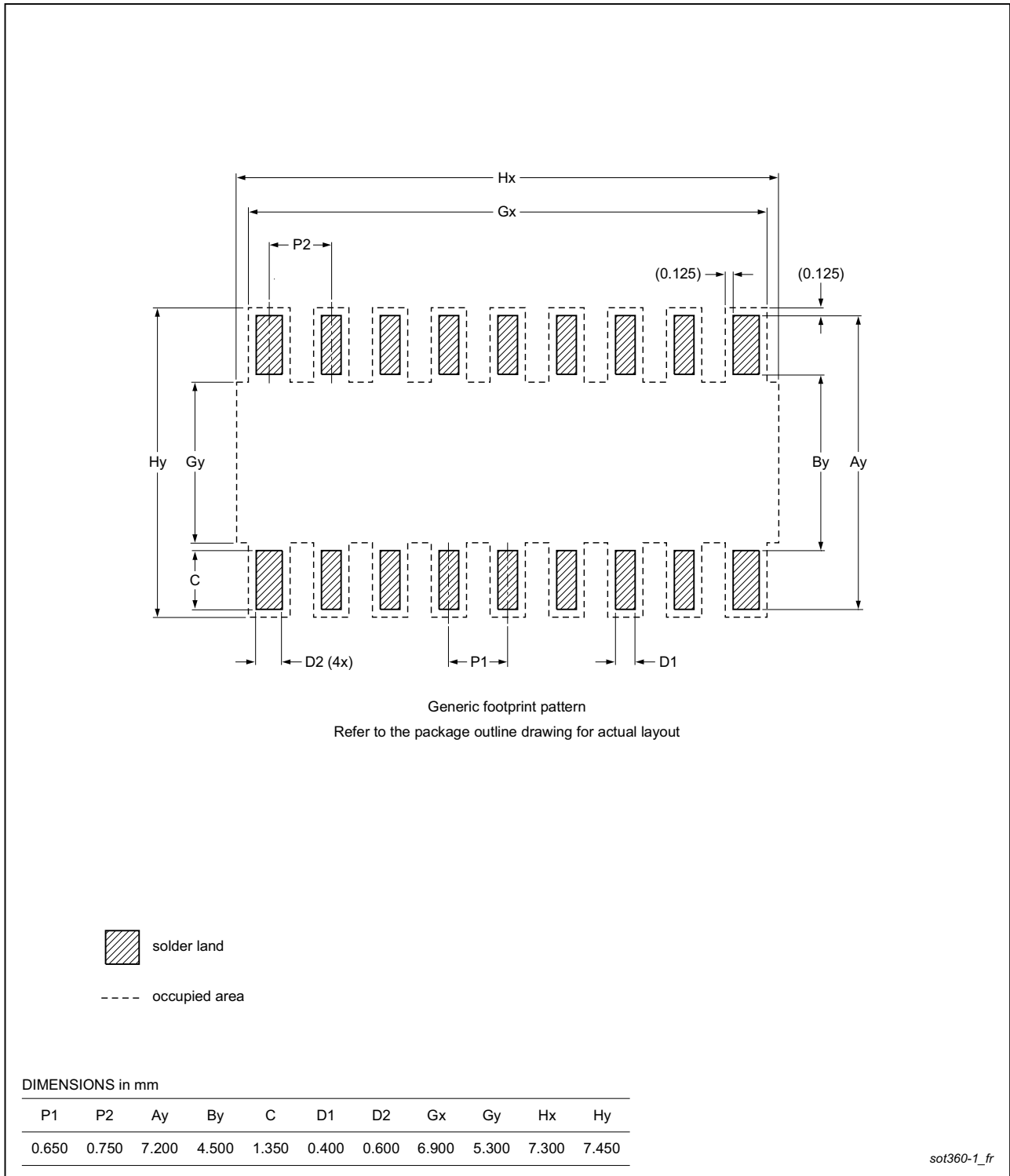


Fig 22. PCB footprint for SOT360-1 (TSSOP20); reflow soldering

Footprint information for reflow soldering of HVQFN20 package

SOT662-1

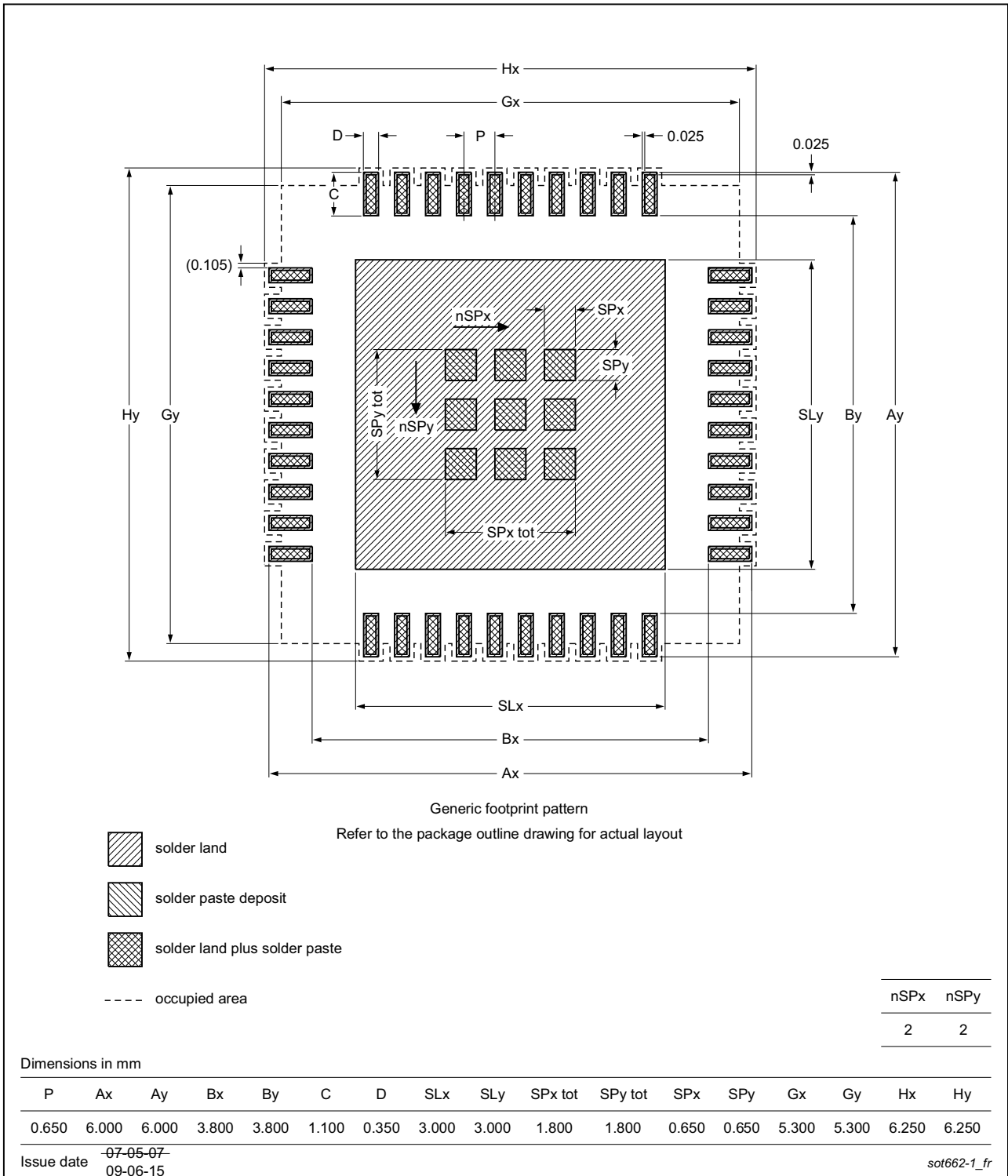


Fig 23. PCB footprint for SOT662-1 (HVQFN20); reflow soldering

## 16. Abbreviations

Table 13. Abbreviations

| Acronym              | Description                  |
|----------------------|------------------------------|
| CDM                  | Charged-Device Model         |
| ESD                  | ElectroStatic Discharge      |
| HBM                  | Human Body Model             |
| I/O                  | Input/Output                 |
| I <sup>2</sup> C-bus | Inter-Integrated Circuit bus |
| LSB                  | Least Significant Bit        |
| PCB                  | Printed-Circuit Board        |
| POR                  | Power-On Reset               |
| SMBus                | System Management Bus        |

## 17. Revision history

Table 14. Revision history

| Document ID                      | Release date  | Data sheet status    | Change notice | Supersedes   |
|----------------------------------|---|----------------------|---------------|--------------|
| PCA9544A v.5                     | 20140423  | Product data sheet   | -             | PCA9544A v.4 |
| Modifications:                   | <ul style="list-style-type: none"> <li>• <a href="#">Section 2 “Features and benefits”</a>, 16th bullet item: deleted phrase “200 V MM per JESD22-A115”</li> <li>• <a href="#">Table 1 “Ordering information”</a>: added “Topside marking” column</li> <li>• <a href="#">Table 2 “Ordering options”</a>: added “Orderable part number”, “Packing method”, and “Minimum order quantity” columns</li> <li>• <a href="#">Table 4 “Control register: Write — channel selection; Read — channel status”</a>: value for INT0, command ‘channel 3 enabled’ corrected from “0” to “X” (correction to documentation only; no change to device)</li> <li>• <a href="#">Section 6.4 “Power-on reset”</a>, first paragraph, third sentence: corrected from “V<sub>DD</sub> must be lowered below 0.2 V to reset the device” to “In order to reset the device, V<sub>DD</sub> must be lowered below 0.2 V for at least 5 μs.” (correction to documentation only; no change to device)</li> <li>• <a href="#">Table 6 “Limiting values”</a>: added limiting value “T<sub>J(max)</sub>”</li> <li>• Added (new) <a href="#">Section 10 “Thermal characteristics”</a></li> <li>• <a href="#">Table 8 “Static characteristics at V<sub>DD</sub> = 2.3 V to 3.6 V”</a>: <ul style="list-style-type: none"> <li>– <a href="#">Table note [2]</a>: inserted phrase “for at least 5 μs”</li> <li>– subsection “Select inputs A0 to A2, <math>\overline{\text{INT0}}</math> to <math>\overline{\text{INT3}}</math>”: Max value for V<sub>IH</sub> corrected from “V<sub>DD</sub> + 0.5 V” to “6 V” (correction to documentation only; no change to device)</li> </ul> </li> <li>• <a href="#">Table 9 “Static characteristics at V<sub>DD</sub> = 4.5 V to 5.5 V”</a>: <ul style="list-style-type: none"> <li>– <a href="#">Table note [2]</a>: inserted phrase “for at least 5 μs”</li> <li>– subsection “Select inputs A0 to A2, <math>\overline{\text{INT0}}</math> to <math>\overline{\text{INT3}}</math>”: Max value for V<sub>IH</sub> corrected from “V<sub>DD</sub> + 0.5 V” to “6 V” (correction to documentation only; no change to device)</li> </ul> </li> <li>• <a href="#">Figure 15 “Definition of timing on the I<sup>2</sup>C-bus”</a> updated (added 0.3 × V<sub>DD</sub> and 0.7 × V<sub>DD</sub> reference lines)</li> <li>• Added <a href="#">Section 15 “Soldering: PCB footprints”</a></li> </ul> |                      |               |              |
| PCA9544A v.4                     | 20090615  | Product data sheet   | -             | PCA9544A v.3 |
| PCA9544A v.3                     | 20081124  | Product data sheet   | -             | PCA9544A v.2 |
| PCA9544A v.2<br>(9397 750 13931) | 20040929  | Product data sheet   | -             | PCA9544A v.1 |
| PCA9544A v.1<br>(9397 750 13301) | 20040728  | Objective data sheet | -             | -            |

## 18. Legal information

### 18.1 Data sheet status

| Document status <sup>[1][2]</sup> | Product status <sup>[3]</sup> | Definition  |
|-----------------------------------|-------------------------------|---|
| Objective [short] data sheet      | Development                   | This document contains data from the objective specification for product development. |
| Preliminary [short] data sheet    | Qualification                 | This document contains data from the preliminary specification.                       |
| Product [short] data sheet        | Production                    | This document contains the product specification.                                     |

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <http://www.nxp.com>.

### 18.2 Definitions

**Draft** — The document is a draft version only. The content is still under internal review and subject to formal approval, which may result in modifications or additions. NXP Semiconductors does not give any representations or warranties as to the accuracy or completeness of information included herein and shall have no liability for the consequences of use of such information.

**Short data sheet** — A short data sheet is an extract from a full data sheet with the same product type number(s) and title. A short data sheet is intended for quick reference only and should not be relied upon to contain detailed and full information. For detailed and full information see the relevant full data sheet, which is available on request via the local NXP Semiconductors sales office. In case of any inconsistency or conflict with the short data sheet, the full data sheet shall prevail.

**Product specification** — The information and data provided in a Product data sheet shall define the specification of the product as agreed between NXP Semiconductors and its customer, unless NXP Semiconductors and customer have explicitly agreed otherwise in writing. In no event however, shall an agreement be valid in which the NXP Semiconductors product is deemed to offer functions and qualities beyond those described in the Product data sheet.

### 18.3 Disclaimers

**Limited warranty and liability** — Information in this document is believed to be accurate and reliable. However, NXP Semiconductors does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information. NXP Semiconductors takes no responsibility for the content in this document if provided by an information source outside of NXP Semiconductors.

In no event shall NXP Semiconductors be liable for any indirect, incidental, punitive, special or consequential damages (including - without limitation - lost profits, lost savings, business interruption, costs related to the removal or replacement of any products or rework charges) whether or not such damages are based on tort (including negligence), warranty, breach of contract or any other legal theory.

Notwithstanding any damages that customer might incur for any reason whatsoever, NXP Semiconductors' aggregate and cumulative liability towards customer for the products described herein shall be limited in accordance with the *Terms and conditions of commercial sale* of NXP Semiconductors.

**Right to make changes** — NXP Semiconductors reserves the right to make changes to information published in this document, including without limitation specifications and product descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof.

**Suitability for use** — NXP Semiconductors products are not designed, authorized or warranted to be suitable for use in life support, life-critical or safety-critical systems or equipment, nor in applications where failure or malfunction of an NXP Semiconductors product can reasonably be expected to result in personal injury, death or severe property or environmental damage. NXP Semiconductors and its suppliers accept no liability for inclusion and/or use of NXP Semiconductors products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk.

**Applications** — Applications that are described herein for any of these products are for illustrative purposes only. NXP Semiconductors makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification.

Customers are responsible for the design and operation of their applications and products using NXP Semiconductors products, and NXP Semiconductors accepts no liability for any assistance with applications or customer product design. It is customer's sole responsibility to determine whether the NXP Semiconductors product is suitable and fit for the customer's applications and products planned, as well as for the planned application and use of customer's third party customer(s). Customers should provide appropriate design and operating safeguards to minimize the risks associated with their applications and products.

NXP Semiconductors does not accept any liability related to any default, damage, costs or problem which is based on any weakness or default in the customer's applications or products, or the application or use by customer's third party customer(s). Customer is responsible for doing all necessary testing for the customer's applications and products using NXP Semiconductors products in order to avoid a default of the applications and the products or of the application or use by customer's third party customer(s). NXP does not accept any liability in this respect.

**Limiting values** — Stress above one or more limiting values (as defined in the Absolute Maximum Ratings System of IEC 60134) will cause permanent damage to the device. Limiting values are stress ratings only and (proper) operation of the device at these or any other conditions above those given in the Recommended operating conditions section (if present) or the Characteristics sections of this document is not warranted. Constant or repeated exposure to limiting values will permanently and irreversibly affect the quality and reliability of the device.

**Terms and conditions of commercial sale** — NXP Semiconductors products are sold subject to the general terms and conditions of commercial sale, as published at <http://www.nxp.com/profile/terms>, unless otherwise agreed in a valid written individual agreement. In case an individual agreement is concluded only the terms and conditions of the respective agreement shall apply. NXP Semiconductors hereby expressly objects to applying the customer's general terms and conditions with regard to the purchase of NXP Semiconductors products by customer.

**No offer to sell or license** — Nothing in this document may be interpreted or construed as an offer to sell products that is open for acceptance or the grant, conveyance or implication of any license under any copyrights, patents or other industrial or intellectual property rights.

4-channel I<sup>2</sup>C-bus multiplexer with interrupt logic

**Export control** — This document as well as the item(s) described herein may be subject to export control regulations. Export might require a prior authorization from competent authorities.

**Non-automotive qualified products** — Unless this data sheet expressly states that this specific NXP Semiconductors product is automotive qualified, the product is not suitable for automotive use. It is neither qualified nor tested in accordance with automotive testing or application requirements. NXP Semiconductors accepts no liability for inclusion and/or use of non-automotive qualified products in automotive equipment or applications.

In the event that customer uses the product for design-in and use in automotive applications to automotive specifications and standards, customer (a) shall use the product without NXP Semiconductors' warranty of the product for such automotive applications, use and specifications, and (b) whenever customer uses the product for automotive applications beyond NXP Semiconductors' specifications such use shall be solely at customer's

own risk, and (c) customer fully indemnifies NXP Semiconductors for any liability, damages or failed product claims resulting from customer design and use of the product for automotive applications beyond NXP Semiconductors' standard warranty and NXP Semiconductors' product specifications.

**Translations** — A non-English (translated) version of a document is for reference only. The English version shall prevail in case of any discrepancy between the translated and English versions.

## 18.4 Trademarks

Notice: All referenced brands, product names, service names and trademarks are the property of their respective owners.

**I<sup>2</sup>C-bus** — logo is a trademark of NXP Semiconductors N.V.

## 19. Contact information

For more information, please visit: <http://www.nxp.com>

For sales office addresses, please send an email to: [salesaddresses@nxp.com](mailto:salesaddresses@nxp.com)

## 20. Contents

|           |  |           |
|-----------|--|-----------|
| <b>1</b>  | <b>General description</b> .....                       | <b>1</b>  |
| <b>2</b>  | <b>Features and benefits</b> .....                     | <b>1</b>  |
| <b>3</b>  | <b>Ordering information</b> .....                      | <b>2</b>  |
| 3.1       | Ordering options .....                                 | 2         |
| <b>4</b>  | <b>Block diagram</b> .....                             | <b>3</b>  |
| <b>5</b>  | <b>Pinning information</b> .....                       | <b>4</b>  |
| 5.1       | Pinning .....  | 4         |
| 5.2       | Pin description .....                                  | 5         |
| <b>6</b>  | <b>Functional description</b> .....                    | <b>6</b>  |
| 6.1       | Device addressing .....                                | 6         |
| 6.2       | Control register .....                                 | 6         |
| 6.2.1     | Control register definition .....                      | 6         |
| 6.3       | Interrupt handling .....                               | 7         |
| 6.4       | Power-on reset .....                                   | 8         |
| 6.5       | Voltage translation .....                              | 8         |
| <b>7</b>  | <b>Characteristics of the I<sup>2</sup>C-bus</b> ..... | <b>9</b>  |
| 7.1       | Bit transfer .....                                     | 9         |
| 7.2       | START and STOP conditions .....                        | 9         |
| 7.3       | System configuration .....                             | 9         |
| 7.4       | Acknowledge .....                                      | 10        |
| 7.5       | Bus transactions .....                                 | 11        |
| <b>8</b>  | <b>Application design-in information</b> .....         | <b>12</b> |
| <b>9</b>  | <b>Limiting values</b> .....                           | <b>13</b> |
| <b>10</b> | <b>Thermal characteristics</b> .....                   | <b>13</b> |
| <b>11</b> | <b>Static characteristics</b> .....                    | <b>14</b> |
| <b>12</b> | <b>Dynamic characteristics</b> .....                   | <b>16</b> |
| <b>13</b> | <b>Package outline</b> .....                           | <b>18</b> |
| <b>14</b> | <b>Soldering of SMD packages</b> .....                 | <b>21</b> |
| 14.1      | Introduction to soldering .....                        | 21        |
| 14.2      | Wave and reflow soldering .....                        | 21        |
| 14.3      | Wave soldering .....                                   | 21        |
| 14.4      | Reflow soldering .....                                 | 22        |
| <b>15</b> | <b>Soldering: PCB footprints</b> .....                 | <b>24</b> |
| <b>16</b> | <b>Abbreviations</b> .....                             | <b>27</b> |
| <b>17</b> | <b>Revision history</b> .....                          | <b>28</b> |
| <b>18</b> | <b>Legal information</b> .....                         | <b>29</b> |
| 18.1      | Data sheet status .....                                | 29        |
| 18.2      | Definitions .....                                      | 29        |
| 18.3      | Disclaimers .....                                      | 29        |
| 18.4      | Trademarks .....                                       | 30        |
| <b>19</b> | <b>Contact information</b> .....                       | <b>30</b> |
| <b>20</b> | <b>Contents</b> .....                                  | <b>31</b> |

Please be aware that important notices concerning this document and the product(s) described herein, have been included in section 'Legal information'.

© NXP Semiconductors N.V. 2014.

All rights reserved.

For more information, please visit: <http://www.nxp.com>

For sales office addresses, please send an email to: [salesaddresses@nxp.com](mailto:salesaddresses@nxp.com)

Date of release: 23 April 2014

Document identifier: PCA9544A